PCMM System Specifications Leica Absolute Tracker and Leica T-Products







Leica Absolute Tracker accuracy

The measurement uncertainty of a coordinate " U_{NYZ} " is defined as the deviation between a measured coordinate and the nominal coordinate of that point. This measurement uncertainty is specified as a function of the distance between the laser tracker and the measured point.

The accuracy specified below is achieved with Leica Geosystems precision reflectors and a measurement mode of 1 second per point under stable environmental conditions

Uxyz, Full Range

(Full Range Definition: 360° horizontally, ± 45° vertically and up to max. distance range of sensor)

AT901-B, AT901-MR, AT901-LR \pm 15 μ m + 6 μ m/m (\pm 0.6 thou + 0.07 thou/ft)

U_{xyz_r} in 2.5 x 5 x 10 m volume (8.2 x 16.4 x 32.8 ft)

(Prerequisite: The laser tracker sensor is anywhere inside the volume)

AT901-B, AT901-MR, AT901-LR \pm 10 μ m + 5 μ m/m (\pm 0.4 thou + 0.06 thou/ft)



Leica Laser Tracker, Leica T-Cam and Leica T-Probe

Ambient conditions

Working temperature $+0^{\circ}\text{C}$ to $+40^{\circ}\text{C}$ (32 F to 104 F) Storage temperature -10°C to $+60^{\circ}\text{C}$ (14 F to 140 F) Relative humidity 10-90%, non-condensing Operational elevation 0-3,050 m (0 - 10,000 ft) Storage elevation 0-21,000 m (0 - 70,000 ft)

Marks of conformity

CB-certified by electrosuisse Yes
CE Yes
Yes
Yes

Feature	Benefit
Robust construction and superior thermal stability with homogenous internal design and non-heat emitting tracker sensor head	Continuous on-spec operation in tough industrial environments with no need for frequent compensation routines; a yearly calibration is all your Leica Absolute Tracker will ever need
Absolute Interferometer utilizing both an absolute distance meter (ADM) and an interferometer (IFM)	A simple, insusceptible, technologically mature design for high-accuracy measurements in all operating conditions; tremendous data redundancies achieved with combined ADM&IFM systems
6 Degrees of Freedom (6DOF) Portable CMM available as an option	The world's only technologically mature PCMM system that can probe like a fixed CMM, scan like a laser scanner and track automated applications – all in one system
Lean construction and compact dimensions, weighing 22 kg and 620 mm in length	Easy one-person transportation and installation, in full compliance with labor department regulations; whole system fits in an average-sized station wagon
ADM/IFM with small beam diameter	Use of small reflectors (0.5") over full measurement range

eica Laser Tracker	AT 901-B	AT 901-MR	AT 901-LR	
(2 sigma specifications)				
Compatibility				
Compatible with Leica T-Cam	No	T-Cam MR	T-Cam LR	
Compatible with Leica T-Probe	No	Yes	Yes	
Compatible with Leica T-Scan	No	Yes	Yes	
Compatible with Leica T-Mac	No	Yes	Yes	
Measurement Volume				
Maximal Volume (Ø)	80 m (262 ft)	50m (164 ft)	80 m (262 ft)	
Horizontal	360°	360°	360°	
/ertical	± 45°	± 45°	± 45°	
Measuring and tracking performa	ince			
Measuring rate	3,0	000 points per seco	ond	
Measuring rate output	1,000 points per second			
Tracking speed lateral	> 4 m/s (13 ft/s)			
Tracking speed radial	> 6 m/s (19 ft/s)			
Acceleration lateral	> 2 g			
Acceleration radial		unlimited		
Laser Interferometer sensor IFM				

633 nm (visible) Wavelength Safety class 21CFR: Safety Class I; IEC 60825-1, Second Edition (2007-03) 50,000 hrs Laser tube MTBF Warm-up time, cold start 8 min Warm-up time, warm start 5 min IFM beam diameter for accurate use of small reflectors 4.0 mm (0.1575 in) Distance resolution 0.32 µm (0.0125 thou) Distance accuracy ± 0.5 ppm

Integrated Absolute Interferometer	Yes	Yes	Yes
Maximal ADM distance	1.0 - 40 m	1.0 - 9 m	1.0 - 40 m
	(3.3 - 131 ft)	(3.3 - 29 ft)	(3.3 - 131 ft
Underlying operational principle	Mod	ulation of polarizat	tion
Wavelength		795 nm (infrared)	
Safety class	21CFR: S	afety Class II; IEC 6	0825-1,
	Seco	ond Edition (2007-	03)
Small beam diameter for			
accurate use of small reflectors	2	2.5 mm (0.0984 in)	
Distance resolution	0	.1 μm (0.004 thou)
Distance accuracy			
over full range	± 2	25 μm (± 0.98 tho	u)
Automated Lock-On			

Accuracy information AT 901-B, AT 901-MR & AT 901-LR

Angular resolution 0.14 arc sec

Angular repeatability, full range \pm 7.5 μ m + 3 μ m/m

and in 2.5 x 5 x 10 m volume \pm 1.5 μ m + 6 μ m/m

Angle accuracy, full range \pm 15 μ m + 6 μ m/m

(\pm 0.59 thou + 0.07 thou/ft)

Angle accuracy in 2.5 x 5 x 10 m volume \pm 15 μ m + 6 μ m/m

(\pm 0.59 thou + 0.07 thou/ft)

Size and weight

when beam broken

 Sensor size
 620 / 290 / 240 mm (24 / 11 / 9 in)

 Sensor weight
 22 kg (48.5 lbs)

 Controller size
 510 / 485 / 200 mm (20 / 19 / 7.9 in)

 Controller weight
 17 kg (37.5 lbs)



AT 901-B, AT 901-LR



AT 901-MR

Leica T-Probe system accuracy

The measurement uncertainty of 3D points "U_{3p}" is defined as the distance between a measured point and the nominal position of that point. This measurement uncertainty is specified as a function of the distance between the laser tracker and the measured point.

The measurement uncertainty of spatial length "U_L" is defined as the deviation between a measured length and its nominal value. This measurement uncertainty is specified as a function of the shortest distance between the laser tracker and the measured length. The length can be up to 6m and is positioned perpendicularly to the laser beam (Leica T-Probe held in constant orientation).

Measurement uncertainty of sphere radius "U_R" is defined as the deviation between a measured sphere radius and its nominal value. This specification assumes a reference sphere with a radius between 10 mm and 50 mm. This measurement uncertainty is specified as a function of the distance between the Laser Tracker and the measured sphere (Leica T-Probe held in constant orientation).

The uncertainty specified below is achieved with Leica T-Probe (110 mm stylus in mount 1/2) and a measurement mode of 1s per point under stable environmental conditions.

Measurement uncertainty of 3D Point (2 sigma) $U_{3D} = 100 \mu m$ if under 7 m (3.94 thou if under 23 ft)

 $U_{\mbox{\tiny 3D}} = 30\ \mu m + 10\ \mu m/m$ if greater than 7 m (1.18 thou + 0.12 thou/ft if greater than 23 ft)

Measurement uncertainty of spatial length (2 sigma) $U_L = \pm 60 \mu m$ if under 8.5 m (\pm 2.36 thou if under 27.9 ft)

 $U_L = \pm 7 \mu m/m$ if greater than 8.5 m (\pm 0.08 thou/ft if greater than 27.9 ft)

Measurement uncertainty of sphere radius (2 sigma) $U_R = \pm 20 \ \mu m + 2 \ \mu m/m \ (\pm 0.79 \ thou + 0.02 \ thou/ft)$

unfiltered measurement data (100%)

	ummered measurem	nent data (100%)
Leica T-Probe	AT901-MR	AT901-LR
Measurement volume Maximal volume (Ø)	18 m (60 ft)	30 m (98 ft)
Horizontal Vertical	360° ± 45°	
Acceptance angle (Freedom to rotate) Pitch angle Jaw angle Roll angle	± 45° ± 45° 360°, unlimited	
Measuring and tracking perform Measuring rate output Tracking speed all directions Acceleration, all directions	rmance 1,000 points per second $\Rightarrow 1 \text{ m/s } (\approx 3.3 \text{ ft/s})$ 1 g	
Weight Leica T-Probe with standard tip and battery Leica T-Probe with standard tip and without battery Leica T-Cam MR and LR	670 g (≈ 1.48 lb) 570 g (≈ 1.26 lb) 4.7 kg (≈ 10.36 lb)	

Comfort through true intelligence

Feature	Benefit
Armless operations	Full "Walk-Around" freedom
Wireless operations	Speed and safety increase
No direct line of sight between probe tip and laser tracker required	Reaches hidden, recessed or hard-to-reach parts without needing to reposition laser tracker
Probe self-identification	Eliminates handling errors
Stylus self-identification	Eliminates handling errors
Acoustic system feedback in your hand	Accelerates measurement process
Visual system feedback in your hand	Accelerates measurement process
Precision quick release for stylus	Flexibility with speed
Wide variation of styli type and length	Highest probing flexibility





Leica AT901-MR gives you a measurement volume of up to 18 m (59 ft), Leica AT901-LR up to 30 m (98 ft)

Leica T-Mac system accuracy

Accuracy of rotation angles

 $0.01^{\circ} = 18 \,\mu\text{m}/100\text{mm} \,(0.71 \,\text{thou per } 3.94")$

Accuray of time stamp <5 µs

Typical positioning accuracy for applications on drilling robots

50 μm (1.97 thou)

Positional accuracy \pm 15 μ m + 6 μ m/m (\pm 0.59 thou + 0.07 thou/ft)

unfiltered measurement data (100%)



Leica T-Mac



1,480 g (≈ 3.26 lb)

01-MR	AT 901-LR	
8 m	30 m	
60 ft)	(98 ft)	
ω π)	(98 π)	
360)°	
± 45	5°	
± 45	5°	
± 45	5°	
360°, unlimited		
1,000 poin	nts per second	
> 1 m/s (≈	3.3 ft/s)	
1 g		
0.01° = 18	μm/100mm	
(0.71 thou	per 3.94")	
۲5 p	JS	
± 15 µm +	6 μm/m	
$(\pm 0.59 \text{ thou} + 0.07 \text{ thou/ft})$		
	± 15 µm +	

Comfort through true intelligence

Feature	Benefit	
Sealed housing	Work in toughest industrial environments	
Robust design, with no internal moving parts or mechanisms	Designed for use in real production environments, easy to service and with no "wear and tear"	
Simple mechanical interface	Direct mounting on a robot or a machine	
Adaptation of tool exchange interface	Automatic connection to robot with high repeatability of under 3 µm (0.12 thou)	
Multiple reflector nests on	Calibrated reflector locations as known home points for easy establishing of object orientation	





Leica T-Scan system accuracy

Measurement uncertainty of spatial length "U_L" is the deviation between a measured length and its nominal value. This measurement uncertainty is specified as a function of the shortest distance between the Laser Tracker and the measured length. The length can be up to 6m and is perpendicular positioned to the laser beam. The centers of two fix-mounted spheres (sphere radius between 15 mm and 20 mm) at the end of the reference length are representing the nominal distance. The measured distance between the sphere centers is calculated using scan data of all four Leica T-Scan sides.

Measurement uncertainty of sphere radius "U_R" is the deviation between a measured sphere radius and its nominal value. The measurement uncertainty of the sphere surface "U_S" is defined as the 2-sigma value of all deviation from the best-fit sphere that is calculated with all measured points. This specification assumes a reference sphere with a radius between 10 mm and 50 mm. These measurement uncertainties are specified as a function of the distance between the Laser Tracker and the sphere. Data of all four Leica T-Scan sides is utilized for the calculation of the sphere radius and the sphere surface.

Measurement uncertainty of plane surface "U_P" is defined as the 2-sigma value of all deviation from the best-fit plane that is calculated with all measured points. Data from all four Leica T-Scan sides is utilized for the calculation of the plane surface.

The uncertainty specified below is achieved with Leica T-Scan using a point density setting of at least 0.35 mm and a line spacing of at least 0.35 mm under stable environmental conditions

Measurement uncertainty of spatial length

 $U_L=\pm\,60~\mu m$ if under 8.5 m (± 2.36 thou if under 27.9 ft) $U_L=\pm\,7~\mu m/m$ if greater than 8.5 m (± 0.08 thou/ft if greater than 27.9 ft)

Measurement uncertainty of sphere radius (2 sigma)

 $U_R = \pm 50 \ \mu m$ if under 8.5 m (± 2.36 thou if under 27.9 ft) $U_R = \pm 7 \ \mu m/m$ if greater than 8.5 m (± 0.08 thou/ft if greater than 27.9 ft)

 $U_s = \pm 95 \, \mu m + 1.5 \, \mu m/m \, (\pm 3.74 \, thou + 0.02 \, thou/ft)$

Measurement uncertainty of plane surface (2 sigma)

 $U_P = \pm 95 \mu m + 3 \mu m/m (\pm 3.74 \text{ thou} + 0.04 \text{ thou/ft})$

The specs shown herein are based on true and unfiltered data.

Typical accuracy on filtered values is about 50% better
than the values shown above.



Leica AT901-MR gives you a measurement volume of up to 18 m (59 ft), Leica AT901-LR up to 30 m (98 ft)

Measurement volume 18 m 30 m Morizontal 360° (98 ft) Vertical ± 45° Acceptance angle ± 45° (Freedom to rotate) ± 45° Pitch angle ± 45° Jaw angle ± 45° Roll angle 360°, unlimited Measuring and tracking performance 7,000 points per second Measuring are output 7,000 points per second Tracking speed all directions 1g Acceleration all directions 1g Leica T-Scan sensor 75 mm (2.95 in) Measuring depth 90 mm (3.54 in) Mean measuring distance 33 mm (3.27 in) Line frequency up to 140 lines/second Measurement sampling rate 10,000 points per second Distance resolution 1 μm (0.04 thou) Point density 0.14 mm - 1.96 mm Accuracy ±30 μm (1.18 thou) Safety class 21CFR: Safety Class II IEC 60825-1; 1993+A1: 1997 + A2: 2001, class 2 Working temperature +16°C to +24°C (61 F to 75 F) Storage temperature +10°C to +60°C (14 F to 140 <th>Leica T-Scan</th> <th>AT 901-MR</th> <th>AT 901-LR</th>	Leica T-Scan	AT 901-MR	AT 901-LR
(Freedom to rotate) Pitch angle Jaw angle Roll angle Measuring and tracking performance Measuring rate output Tracking speed all directions Acceleration all directions Acceleration all directions Leica T-Scan sensor Measuring depth Mean scan width Mean measuring distance Line frequency Measurement sampling rate Distance resolution Point density Accuracy Safety class IEC 60825-1; 1993+A1: Page 145° 360°, unlimited 7,000 points per second 1 m/s (≈ 3.3 ft/s) 75 mm (2.95 in) 90 mm (3.54 in) 83 mm (3.27 in) up to 140 lines/second 10,000 points per second 10,000 points per second 1 μm (0.04 thou) 0.14 mm − 1.96 mm (5.5 thou − 77.2 thou) ±30 μm (1.18 thou) Safety class IEC 60825-1; 1993+A1: 1997 + A2: 2001, class 2 Working temperature 16°C to +24°C (61 F to 75 F) -10°C to +60°C (14 F to 140)	Maximal volume (0) Horizontal		(98 ft)
tracking performance Measuring rate output Tracking speed all directions Acceleration all directions Acceleration all directions Leica T-Scan sensor Measuring depth Mean scan width Mean measuring distance Line frequency Measurement sampling rate Distance resolution Point density Accuracy Safety class IEC 60825-1; 1993+A1: Tomas for the first output (1,000 points per second) 1 μm (0.04 thou) 1 μm (0.04 thou) 1 μm (0.04 thou) 1 μm (1.18 thou) 21CFR: Safety Class II 1997 + A2: 2001, class 2 Working temperature Tracking performance 7,000 points per second 75 mm (2.95 in) 90 mm (3.54 in) 83 mm (3.27 in) 10,000 points per second 10,000 points per second 10,000 points per second 21 μm (0.04 thou) 21 CFR: Safety Class II 1997 + A2: 2001, class 2	(Freedom to rotate) Pitch angle Jaw angle	360	± 45°
Measuring depth 75 mm (2.95 in) Mean scan width 90 mm (3.54 in) Mean measuring distance 83 mm (3.27 in) Line frequency up to 140 lines/second Measurement sampling rate 10,000 points per second Distance resolution 1 μm (0.04 thou) Point density 0.14 mm - 1.96 mm (5.5 thou - 77.2 thou) ±30 μm (1.18 thou) Safety class 21CFR: Safety Class II IEC 60825-1; 1993+A1: 1997 + A2: 2001, class 2 Working temperature +16°C to +24°C (61 F to 75 F) Storage temperature -10°C to +60°C (14 F to 140	tracking performance Measuring rate output Tracking speed all directions		/s (≈ 3.3 ft/s)
IEC 60825-1; 1993+A1: $ 1997 + A2: 2001, class 2 $ Working temperature $ +16^{\circ}\text{C to } +24^{\circ}\text{C } (61 \text{ F to } 75 \text{ F}) $ Storage temperature $ -10^{\circ}\text{C to } +60^{\circ}\text{C } (14 \text{ F to } 140 $	Measuring depth Mean scan width Mean measuring distance Line frequency Measurement sampling rate Distance resolution Point density	90 mm (3.54 in) 83 mm (3.27 in) up to 140 lines/second 10,000 points per second 1 µm (0.04 thou) 0.14 mm - 1.96 mm (5.5 thou - 77.2 thou)	
Storage temperature -10°C to +60°C (14 F to 140	,		,
	Storage temperature		

Leica

Feature	Benefit	
Measurement volume of up to 30 m (98 ft)	Measure large object without repositioning laser tracker	
20% weight reduction and 30% smaller volume than previous model	Improved portability, ease of use on long, demanding jobs and better access to toght spaces with difficult geometries	
Optmized marker positions	More accurate 6DOF readings over the full range of scanner positions	
"Instant Temperature Compensation"	No-nonsense measurements in almost any environment without user intervention	
Enhanced operator feedback with new intuitive LED pattern	Accurate information about optimal scanning distance	
Improved ergonomics with optimized handle design and reduced weight	Leica T-Scan is the most comfortable- to-work-with hand-held laser scanner in the industry	

Whether building the fastest car, the biggest plane or the most precise tooling, you need exact measurements to improve quality and productivity. So when it has to be right, professionals trust Leica Geosystems metrology products to help collect, analyze and present 3-dimensional (3D) data for industrial measurement.

Leica Geosystems Metrology is best known for its broad array of control and industrial measurement products, including high-precision industrial theodolites and total stations, laser trackers and 6 Degrees of Freedom-based (6DOF) Portable CMM systems. The latter include the Leica T-Probe handheld armless probe, Leica T-Scan hand-held laser scanner and Leica T-Mac tracking device for automated applications. Leica Geosystems also offers a broad range of 3D metrology software solutions. Those who use the metrology products by Leica Geosystems every day trust them for their dependability, the value they deliver and the world-class service and support that's second to none.

Precision, reliability and service from Leica Geosystems metrology products.

When it has to be right.

764365 I.2008 © Copyright 2008 – Leica Geosystems AG, Unterentfelden, Switzerland

For more information, please contact info.metrology@leica-geosystems.com



Leica Absolute Tracker Product Brochure Art. 764370



Metrology Products Catalog 2008 Art. 751789

Leica Geosystems AG
Metrology Products
Moenchmattweg 5
CH-5035 Unterentfelden
Switzerland
Phone +41 62 737 67 67
Fax +41 62 723 07 34
info.metrology@leica-geosystems.com

www.leica-geosystems.com/metrology



